UNIVERSITY OF CAMBRIDGE INTERNATIONAL EXAMINATIONS

GCE Advanced Subsidiary Level and GCE Advanced Level

MARK SCHEME for the October/November 2009 question paper for the guidance of teachers

9709 MATHEMATICS

9709/41

Paper 41, maximum raw mark 50

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

Mark schemes must be read in conjunction with the question papers and the report on the examination.

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CIE is publishing the mark schemes for the October/November 2009 question papers for most IGCSE, GCE Advanced Level and Advanced Subsidiary Level syllabuses and some Ordinary Level syllabuses.

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Mark Scheme Notes

Marks are of the following three types:

- M Method mark, awarded for a valid method applied to the problem. Method marks are not lost for numerical errors, algebraic slips or errors in units. However, it is not usually sufficient for a candidate just to indicate an intention of using some method or just to quote a formula; the formula or idea must be applied to the specific problem in hand, e.g. by substituting the relevant quantities into the formula. Correct application of a formula without the formula being quoted obviously earns the M mark and in some cases an M mark can be implied from a correct answer.
- A Accuracy mark, awarded for a correct answer or intermediate step correctly obtained. Accuracy marks cannot be given unless the associated method mark is earned (or implied).
- B Mark for a correct result or statement independent of method marks.
- When a part of a question has two or more "method" steps, the M marks are generally independent unless the scheme specifically says otherwise; and similarly when there are several B marks allocated. The notation DM or DB (or dep*) is used to indicate that a particular M or B mark is dependent on an earlier M or B (asterisked) mark in the scheme. When two or more steps are run together by the candidate, the earlier marks are implied and full credit is given.
- The symbol √ implies that the A or B mark indicated is allowed for work correctly following on from previously incorrect results. Otherwise, A or B marks are given for correct work only. A and B marks are not given for fortuitously "correct" answers or results obtained from incorrect working.
- Note: B2 or A2 means that the candidate can earn 2 or 0.
 B2/1/0 means that the candidate can earn anything from 0 to 2.

The marks indicated in the scheme may not be subdivided. If there is genuine doubt whether a candidate has earned a mark, allow the candidate the benefit of the doubt. Unless otherwise indicated, marks once gained cannot subsequently be lost, e.g. wrong working following a correct form of answer is ignored.

- Wrong or missing units in an answer should not lead to the loss of a mark unless the scheme specifically indicates otherwise.
- For a numerical answer, allow the A or B mark if a value is obtained which is correct to 3 s.f., or which would be correct to 3 s.f. if rounded (1 d.p. in the case of an angle). As stated above, an A or B mark is not given if a correct numerical answer arises fortuitously from incorrect working. For Mechanics questions, allow A or B marks for correct answers which arise from taking *g* equal to 9.8 or 9.81 instead of 10.

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The following abbreviations may be used in a mark scheme or used on the scripts:

AEF	Any Equivalent Form (of answer is equally acceptable)
AG	Answer Given on the question paper (so extra checking is needed to ensure that the detailed working leading to the result is valid)
BOD	Benefit of Doubt (allowed when the validity of a solution may not be absolutely clear)
CAO	Correct Answer Only (emphasising that no "follow through" from a previous error is allowed)
CWO	Correct Working Only – often written by a 'fortuitous' answer
ISW	Ignore Subsequent Working
MR	Misread
PA	Premature Approximation (resulting in basically correct work that is insufficiently accurate)
sos	See Other Solution (the candidate makes a better attempt at the same question)
SR	Special Ruling (detailing the mark to be given for a specific wrong solution, or a case where some standard marking practice is to be varied in the light of a particular circumstance)

Penalties

- MR −1 A penalty of MR −1 is deducted from A or B marks when the data of a question or part question are genuinely misread and the object and difficulty of the question remain unaltered. In this case all A and B marks then become "follow through √" marks. MR is not applied when the candidate misreads his own figures this is regarded as an error in accuracy. An MR −2 penalty may be applied in particular cases if agreed at the coordination meeting.
- PA –1 This is deducted from A or B marks in the case of premature approximation. The PA –1 penalty is usually discussed at the meeting.

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1	$[15000 = 750v_A, 15000 = 500v_B]$	M1		$V_{conversion} = D = V_{conversion}$
				For using $P = Fv$
	Speeds are 20ms ⁻¹ and 30ms ⁻¹	A1		7
	[KE gain = $\frac{1}{2}$ 1000(30 ² – 20 ²)]	M1	_	For using $KE = \frac{1}{2} \text{ mv}^2$
	Increase is 250 000J (or 250kJ)	A1ft	4	$ft 500(v_B^2 - v_A^2)$
2	(i) $[mgh = \frac{1}{2} m6^2]$	M1	_	For using PE loss = KE gain
	Height is 1.8m	A1	2	
	(ii) $\frac{1}{2}$ mv ² = mg(1.8 + 0.65) or	D16		
	$\frac{1}{2} \text{ mv}^2 - \frac{1}{2} \text{ m6}^2 = \text{mg} \times 0.65$	B1ft	_	
	Maximum speed is 7ms ⁻¹	B1	2	
3				For resolving forces parallel to or
				perpendicular to:-
				the force of magnitude QN, or
		M1		the resultant
	$Q - P\cos 60^{\circ} = 12\cos 80^{\circ} \text{ and } P\sin 60^{\circ} = 12\sin 80^{\circ}$			
	$Q\cos 80^{\circ} + P\cos 40^{\circ} = 12 \text{ and } P\sin 40^{\circ} = Q\sin 80^{\circ}$	A1		
	$[Q - 12\sin 80^{\circ}\cos 60^{\circ}/\sin 60^{\circ} = 12\cos 80^{\circ}$			For eliminating P
	$Q\cos 80^{\circ} + Q\sin 80^{\circ}\cos 40^{\circ}/\sin 40^{\circ} = 12]$	M1	_	
	Q = 8.91	A1	4	
	(Direct - 14			
	(First alternative)	MO		For manufacional formana mana to D
	$Q\cos 30^{\circ} = 12\cos 50^{\circ}$	M2 A1		For resolving forces perp. to P
	Q = 8.91	A1	4	
	Q = 8.91	Aı	4	
	(Second alternative)			For triangle of forces with sides P, Q
	(Second afternative)			and 12, and values of any 2 angles
				shown or implied (Note P, Q and –R are
		M1		in equil.)
	Angles opposite Q and 12 are 40° and 60°	1111		qs,
	respectively	A 1		
	$Q/\sin 40^{\circ} = 12/\sin 60^{\circ}$	M1		For using the sine rule
	Q = 8.91	A1	4	2 3,20 2 3,10
		-	-	
	(Third alternative)			
	•			For force diagram showing P, Q and –R,
		M1		and values of any 2 angles at 'O' shown.
	Angle between P and Q is 120° and between P and			-
	-R is 140°	A 1		
	$[Q/\sin 140^{\circ} = 12/\sin 120^{\circ}]$	M1		For using Lami's theorem
	Q = 8.91	A1	4	

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4	(i)	For angle between AP and vertical =			
	()	36.9° (or sin ⁻¹ 0.6) or for angle between			
		PS and vertical = 53.1°			
		$(or sin^{-1}0.8)$	B1		May be implied
					For resolving forces on P in the direction
		$[T_{PS} + (T_{PA}\cos 90^{\circ}) = 5\sin 36.9^{\circ}]$	M1		of PS (2 non–zero terms required)
		rst alternative)			
		the angle between PA and the horizontal			
		ough P is 53.1° and the angle between PS and	D1		March a locally d
	tne	horizontal through P is 36.9°	B1		May be implied
	[0.6	$6T_{PA} = 0.8T_{PS}$ and $0.8T_{PA} + 0.6T_{PS} = 5$			For resolving forces on P vertically and
	-	$\{0.8(0.8/0.6) + 0.6\}$ T _{PS} = 5]	M1		horizontally and eliminating T _{PA}
		cond alternative)			
		Δ of forces with sides T_{PA} , T_{PS} and 5, with			
	ang	les opposite T _{PS} and 5 shown as 36.9° and 90°	D1		May be implied
	ГТ	$_{\rm S} = 5 \sin 36.9^{\rm o}$	B1 M1		May be implied For using trig. in Δ
	[1 ps	§ – 38III30.9]	1V1 1		ror using arg. in Δ
	Th	ird alternative)			
	-	force diag. showing T _{PA} , T _{PS} and 5, with			
		les between T_{PS} and T_{PA} , and between 5 and			
		being shown as 90° and 143.1°	B1		May be implied
	$[T_{PS}]$	$\sqrt{\sin 143.1^{\circ}} = 5/\sin 90^{\circ}$	M1		For using Lami's rule
	 Ten	asion is 3N	A1	3	Accept 3.00
	(;;)	$[F = T \cos(\sin^{-1}0.6)]$	M1		For resolving forces on S horizontally
	(11)	Frictional force is 2.4N	A1	2	Accept 2.40
		Thetional force is 2.410	711	2	Лесері 2.40
	(iii)	R = 2.4/0.75	B1ft		
		$[W + T \sin(\sin^{-1}0.6) = R]$	M1		For resolving forces on S vertically
		W = 1.4	A1ft	3	ft W = $7T/15$ or W = $4F/3 - 1.8$
5	(i)		M1		For using Newton's second law
	()	$-F - 0.6gsin 18^{\circ} = 0.6(-4)$	A 1		
		Frictional component is 0.546N	A1		
		FD 0.6 4007			
		$[R = 0.6g\cos 18^{\circ}]$	M1		For resolving forces normal to the plane
		Normal component is 5.71N Coefficient is 0.096	A1	4	
		Coefficient is 0.090	B1ft	6	
	(ii)	$0.6g\sin 18^{\circ} - 0.546 = 0.6a$ or			
	\ '	$2(0.6g\sin 18^{\circ}) = 0.6(a+4)$	B1ft		
		a = 2.18	B1	2	
					didates who use 'a' for the upwards
					n, instead of as defined in the question.
			_		$^{\circ} + 0.546 = 0.6a \Rightarrow a = -2.18$ B1
					companied by satisfactory explanation for
<u></u>			uropp	ing tr	ne minus sign. B1

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6	(i)				
					For using Newton's second law to P or
			3.71		O or for using $a = M - m$
			M1		Q, or for using $a = \frac{M - m}{M + m}g$
		0.55g - T = 0.55a and $T - 0.45g = 0.45a$ or			
		a = [(0.55 - 0.45)/(0.55 + 0.45)]g	A1		
		Acceleration is 1ms ⁻²	A1	3	
	(ii)	(a)	3.54		For using $s = 5 - \frac{1}{2} a2^2$ for P or
		H : 1, CD: 2 11 : 1, CO: 7	M1	2	$s = 5 + \frac{1}{2} a2^2$ for Q
		Height of P is 3m and height of Q is 7m	Alft	2	ft 5 – 2a and 5 + 2a
		(b) Speed is 2ms ⁻¹	B1ft	1	ft 2a
	(iii)				For using $s = ut + \frac{1}{2}gt^2$ for P or for Q
	(111)	$[3 = 2t_P + 5t_P^2, 7 = -2t_O + 5t_O^2]$	M1		(NB $a = g$)
		$t_{\rm P}=0.6$	A1		(1.12 a g)
		v _r old			
					Accept $t_0 = 0.2 + 1.2$ following
					consideration of upward and downward
		$t_{Q} = 1.4$	A1		motion under gravity of Q separately
		Q is 0.8s later than P	A1	4	AG
7	(2)	Cuandia (ma ⁻¹	D1		
7	(i)	Speed is 6ms^{-1} a = 0.6	B1 B1ft	2	ft v/10
		a = 0.0	DIII	2	11 1/10
	(ii)		M1		For differentiating v(t)
	(ii)	$a(t) = -1600/t^3 \text{ (second stage)}$	M1 A1		For differentiating v(t)
	(ii)	$a(t) = -1600/t^3 \text{ (second stage)}$ $[0.6 = 1600/t^3 \rightarrow t^3 = (1600/0.6)]$			For differentiating $v(t)$ For attempting to solve $a(t) = -0.6$
	(ii)		A1	4	
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max 5/6)}$
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max 5/6)}$ Speed is 6ms^{-1} B1
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1
	(ii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1
		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1
		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1
		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$ $s_1 = 30m$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1
,		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1 For integrating $v(t)$
		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$ $s_1 = 30m$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1 For using limits 10, 20 or for using
		$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$ $s_1 = 30m$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ M1 $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1 For integrating $v(t)$
	(iii)	$[0.6 = 1600/t^3 \implies t^3 = (1600/0.6)]$ $t = 13.9$ $s_1 = 30m$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6\text{)}$ Speed is 6ms^{-1} B1 For differentiating $v(t)$ $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1 For using limits 10, 20 or for using $s(10) = s_1$ to find $c = 130$ and
	(iii)	$[0.6 = 1600/t^{3} \implies t^{3} = (1600/0.6)]$ $t = 13.9$ $s_{1} = 30m$ $s = (800t^{-1})/(-1) - 2t (+ C)$	A1 M1 A1	4	For attempting to solve $a(t) = -0.6$ SR in parts (i) and (ii) (treated as a single entity) for candidates who assume there is necessarily continuity of acceleration at $t = 10 \text{ (max } 5/6$) Speed is 6ms^{-1} B1 For differentiating $v(t)$ $a(t) = -1600/t^3$ A1 $a = a(10) = -1.6$ B1 For $t = \sqrt[3]{\frac{-1600}{1.6}}$ B1 For integrating $v(t)$ For using limits 10, 20 or for using $s(10) = s_1$ to find $c = 130$ and evaluating $s(20)$.